# Curvature on reductive homogeneous spaces 

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#### Abstract

Here we consider the general flag manifold $\mathbb{F}_{\Theta}$ as a naturally reductive homogeneous space endowed with an $U$-invariant metric $\Lambda^{\Theta}$ and an invariant almost-complex structure $J^{\Theta}$. The main objective of this work is to explore the riemannian connection associated with the metric $\Lambda^{\Theta}$ in order to calculate some classes of curvatures which should allow us to confirm, in a simple way, that flag manifolds are either not biholomorfically equivalent nor holomorphically isometric to any complex projective space. Keywords. Homogeneous spaces, flag manifolds, riemannian connection, curvature.


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Resumen. Consideramos aquí la variedad bandera general $\mathbb{F}_{\Theta}$ como un espacio homogéneo naturalmente reductivo dotado con una métrica $U$-invariante $\Lambda^{\Theta}$ y una estructura cuasicompleja invariante $J^{\Theta}$. El objetivo principal de este trabajo es explorar la conexión riemanniana asociada con la métrica $\Lambda^{\Theta}$ con el fin de calcular algunas clases de curvaturas las cuales nos permitan confirmar, de manera simple, que las variedades bandera no son bilomórficamente equivalentes ni holomórficamente isométricas a ningún espacio proyectivo complejo.

## 1. Introduction

The main purpose of this paper is to study the curvature on the generalized flag manifold associated with semi-simple complex Lie algebras and groups. Given a complex semi-simple Lie group $G$, its "fundamental homogeneous space" is the coset space $\mathbb{F}_{\Theta}=G / P_{\Theta}$ modulo a parabolic subgroup (Borel subgroup)

[^0]$P_{\Theta}$ of $G$, where $\Theta$ is a subset of simple roots of $\mathfrak{g}$, the Lie algebra of $G$. In the context of compact Lie groups, the spaces $G / P_{\Theta}$ are given by coset $U / K_{\Theta}$ where $U$ is a compact real form of $G$ and $K_{\Theta}=U \cap P_{\Theta}$ is the centralizer of a torus of $U$, when $\Theta=\emptyset$ the torus is maximal and we denote $\mathbb{F}=U / T$ as the maximal flag manifold. These spaces are also known generically as "generalized flag manifolds", since $G / P_{\Theta}$ can be identified with the concrete space of flags of subspaces of an $n$-dimensional complex vector space when $G$ is the special linear group $S l(n, C)$. We directly use the algebra (combinatorics) of root systems, which gives life to the theory of semi-simple Lie algebras, to find the form of the riemannian connection of $\mathbb{F}_{\Theta}$ associated to the invariant metric $\Lambda^{\Theta}$ and then we calculate some curvatures, in order to relate them with some topological and geometrical properties of $\mathbb{F}_{\Theta}$. In particular, the results reaffirm that a Kähler maximal flag manifold, different from $\mathbb{F}(2)$, can not be bi-holomorphic equivalent, or isometric holomorphic, to any projective space $\mathbb{C} P(n)$.

## 2. Preliminaries

Let $G$ be a connected Lie group, $H$ its closed subgroup, $g$ an invariant riemannian metric on the homogenous space $G / H$. Denote by $\mathfrak{g}$ and $\mathfrak{h}$ the Lie algebras corresponding to $G$ and $H$, respectively. $G / H$ is a reductive homogeneous space if the Lie algebra $\mathfrak{g}$ can be decomposed into a vector space direct sum of the $\mathfrak{h}$ and an $a d(H)$-invariant subspace $\mathfrak{m}$, that is, if
(1) $\mathfrak{g}=\mathfrak{h}+\mathfrak{m}, \quad \mathfrak{h} \cap \mathfrak{m}=0$;
(2) $\operatorname{ad}(H) \mathfrak{m} \subset \mathfrak{m}$.

Condition (2) implies $[\mathfrak{h}, \mathfrak{m}] \subset \mathfrak{m}$. We identify $\mathfrak{m}$ with the tangent space $T_{[H]}(G / H)$, the invariant metric $g$ is completely defined by its value at the point $[H]$.

Recall that $(G / H, g)$ is naturally reductive [10] if

$$
g\left([X, Y]_{\mathfrak{m}}, Z\right)=g\left(X,[Y, Z]_{\mathfrak{m}}\right)
$$

for all $X, Y, Z \in \mathfrak{m}$. Here $[\cdot, \cdot]_{\mathfrak{m}}$ denotes the projection of $\mathfrak{g}$ onto $\mathfrak{m}$ with respect to the reductive decomposition.

Let $\mathfrak{g}$ be a semi-simple complex Lie algebra, $\mathfrak{h} \subseteq \mathfrak{g}$ a Cartan subalgebra of $\mathfrak{g}$, that is, a nilpotent subalgebra such that its normalizer is itself or equivalently if $[X, \mathfrak{h}] \subset \mathfrak{h}$ then $X \in \mathfrak{h} ; \alpha$ be a linear functional on the complex vectorial space $\mathfrak{h}$ and denote for $\mathfrak{g}_{\alpha}$ the linear space of $\mathfrak{g}$ given by

$$
\mathfrak{g}_{\alpha}=\{X \in \mathfrak{g} \quad: \quad[H, X]=\alpha(H) X, \text { for all } H \in \mathfrak{h}\}
$$

Note that for $\alpha=0, \mathfrak{g}_{\alpha}=\mathfrak{h}$. The linear functional $\alpha$ is called a root (of $\mathfrak{g}$ with respect to $\mathfrak{h}$ ) if $\alpha \neq 0$ and $\mathfrak{g}_{\alpha} \neq\{0\}$. In such case $\mathfrak{g}_{\alpha}$ is called a root subspace. Denote by $\Pi$ the set of roots of the pair $(\mathfrak{g}, \mathfrak{h})$ and by $B$ the Cartan-Killing form in $\mathfrak{g} \times \mathfrak{g}$, that is,

$$
B(X, Y)=\langle X, Y\rangle=\operatorname{tr}(\operatorname{ad} X \circ \operatorname{ad} Y),
$$

for all $X, Y \in \mathfrak{g}$. Since $\mathfrak{g}$ is semi-simple, $B$ is not degenerated on $\mathfrak{g} \times \mathfrak{g}$, and its restriction to $\mathfrak{h} \times \mathfrak{h}$ is not degenerated either, for each $\alpha \in \Pi$ exists a unique $H_{\alpha} \in \mathfrak{h}$ such that $B\left(H, H_{\alpha}\right)=\left\langle H, H_{\alpha}\right\rangle=\alpha(H)$, for all $H \in \mathfrak{h}$. Let $(\alpha, \beta)=B\left(H_{\alpha}, H_{\beta}\right)$ then $(\cdot, \cdot)$ is a symmetric not degenerated bilinear form on $\mathfrak{h}^{*}$.

Theorem 2.1. [21] If $\mathfrak{g}$ is a semi-simple complex Lie algebra and $\mathfrak{h}$ is a Cartan subalgebra of $\mathfrak{g}$ then
(1) $\mathfrak{g}$ admits a decomposition in root spaces $\mathfrak{g}=\mathfrak{h} \bigoplus_{\alpha \in \Pi} \mathfrak{g}_{\alpha}$.
(2) The root spaces $\mathfrak{g}_{\alpha}, \alpha \in \Pi$ have complex dimension one.
(3) If $\alpha$ and $\beta$ are any two roots (including 0 ) and $\beta \neq-\alpha$, then $\mathfrak{g}_{\alpha}$ and $\mathfrak{g}_{\beta}$ are orthogonal with respect to $B$.
(4) If $\alpha$ is a not null root, then $\pi \cap \mathbb{Z}\{\alpha\}=\{\alpha,-\alpha\}$.
(5) For each $\alpha \in \Pi$ exists a vector $X_{\alpha} \in \mathfrak{g}_{\alpha}$ such that for all $\alpha, \beta \in \Pi$ we have:
(a) $\left[X_{\alpha}, X_{-\alpha}\right]=H_{\alpha},\left[H, X_{\alpha}\right]=\alpha(H) X_{\alpha}($ for all $H \in \mathfrak{h})$;
(b) $\left[X_{\alpha}\right]=0$ if $\alpha+\beta \neq 0$ and $\alpha+\beta \notin \Pi$;
(c) $\left\langle X_{\alpha}, X_{\beta}\right\rangle=1$ if $\alpha+\beta=0$ and $\left\langle X_{\alpha}, X_{\beta}\right\rangle=0$ in the other cases. $\left[X_{\alpha}, X_{\beta}\right]=m_{\alpha, \beta} X_{\alpha+\beta}$, if $\alpha+\beta \in \Pi$ with, $m_{\alpha \beta} \in \mathbb{R}$, and

$$
\begin{align*}
m_{-\alpha,-\beta} & =-m_{\alpha, \beta} \\
m_{-\alpha, \alpha+\beta} & =m_{\alpha+\beta,-\beta}  \tag{2.1}\\
& =m_{-\beta,-\alpha}
\end{align*}
$$

The set $\left\{X_{\alpha}: \alpha \in \Pi\right\}$ in this theorem satisfying item 5 is called a Weyl base or Cartan-Weyl base of $\mathfrak{g}$ modulo $\mathfrak{h}$.

Theorem 2.2. [21] Let $\mathfrak{g}$ be a semi-simple complex Lie algebra, $\mathfrak{h}$ a Cartan subalgebra of $\mathfrak{g}$, and $\Pi$ the associated root system. We denote for $\mathfrak{h}_{\mathbb{R}}$ the subspace of $\mathfrak{g}$ generated on $\mathbb{R}$ for $H_{\alpha}, \alpha \in \Pi$.
(1) The restriction of the Cartan-Killing form B of $\mathfrak{g}$ to $\mathfrak{k}$ is real and strictly positive on $\mathfrak{h}_{\mathbb{R}} \times \mathfrak{h}_{\mathbb{R}}$.
(2) $\mathfrak{h}=\mathfrak{h}_{\mathbb{R}}+\sqrt{-1} \mathfrak{h}_{\mathbb{R}}$.

Theorem 2.3. [21] Let $\Pi^{+} \subset \Pi$ be the set of positive roots of the pair $(\mathfrak{g}, \mathfrak{h})$. Suppose that $l$ is the rank of $\mathfrak{g}$, then there exists a root subset $\Sigma=\left\{\alpha_{1} \ldots, \alpha_{l}\right\}$ with the following properties:
(i) Each $\alpha_{i} \in \Sigma, 1 \leq i \leq l$, can not be written as a sum of other positive roots.
(ii) Each root $\alpha \in \Pi$ can be written as a linear combination of elements of $\sigma$, with coefficient integers, that is $\alpha=\sum_{i=1}^{l} n_{i} \alpha_{i}$ with $n_{i}$ integer number for $i=1, \ldots, l$.

A root subset $\Sigma$ with the properties listed in the Theorem 2.3 will be called a simple system of roots.

Definition 2.4. [15] A real Lie algebra is said to be compact if its CartanKilling form is negative definite on it.

Theorem 2.5. [15] All semi-simple complex Lie algebra $\mathfrak{g}$ admits compact real forms. If $\mathfrak{u}_{1}$ and $\mathfrak{u}_{2}$ are two compact real forms of $\mathfrak{g}$, then there is an automorphism $\phi$ of $\mathfrak{g}$ such that $\phi\left(\mathfrak{u}_{1}\right)=\mathfrak{u}_{2}$ therefore, the two real forms are isomorphic.

Definition 2.6. [8] Let $\mathfrak{g}$ be a Lie algebra and $\mathfrak{a}$ a subalgebra of $\mathfrak{g}$. We said that $\mathfrak{a}$ is a Borel subalgebra if it is a soluble maximal subalgebra.

Definition 2.7. [8] Let $\mathfrak{g}$ be a Lie algebra. A subalgebra $\mathfrak{p}$ of $\mathfrak{g}$ is called a parabolic subalgebra, if $\mathfrak{p}$ contains any Borel subalgebra.

## 3. Flag manifolds as a naturally reductive homogeneous space

A flag manifold is a naturally reductive homogeneous space. In fact it is the homogeneous space $G / C(S)$ where $G$ is a semi-simple Lie group and $C(S)$ is the centralizer of the torus $S$ (not necessarily maximal in $G$.) When $S$ is a maximal torus, the flag manifold is called maximal or total and we will denote it by $\mathbb{F}$.

For example, in the classical case $G$ is the special unitary group and $C(S)$ must be conjugated to a subgroup of the form $S\left(U_{n_{1}} \times U_{n_{2}} \times \cdots \times U_{n_{k}}\right)$, with $n_{1}, n_{2}, \ldots, n_{k}$ positive integers satisfying $n_{1}+n_{2}+\cdots+n_{k}=n$. If $m_{i}=$ $n_{1}+\cdots+n_{i}$, the quotient $S U_{n} / S\left(U_{n_{1}} \times \cdots \times U_{n_{k}}\right)$ can be identified with the set $\mathbb{F}\left(m_{1}, \ldots, m_{k}\right)$ of "partial flags" $\{0\}=E_{0} \subset E_{m_{1}} \subset \cdots \subset E_{m_{k}-1} \subset E_{m_{k}}=\mathbb{C}^{n}$, where $E_{i}$ is an $i$-dimensional subspace of $\mathbb{C}^{n}$. The case $n_{r}=1$ for all $1 \leq r \leq k$ is denoted by $\mathbb{F}(n)$ and it can be identified with the set of the "total flags" $\{0\}=E_{0} \subset E_{1} \subset \cdots \subset E_{n-1} \subset E_{n}=\mathbb{C}^{n}$.

Now, if we consider the general case, flag manifolds have a characterization in terms of root theory as follows: let $\mathfrak{g}$ be a semi-simple complex Lie algebra and $\mathfrak{h}$ a Cartan subalgebra of $\mathfrak{g}$, we denote by $\Pi$ the set of roots of the pair $(\mathfrak{g}, \mathfrak{h})$. In the sequel we fix a Weyl basis of $\mathfrak{g}$ as in item 5 of the Theorem 2.1. Let $\Pi^{+} \subset \Pi$ a choice of positive roots. We denote with $\Sigma$ the corresponding simple root system. Let $\Theta$ be a subset of $\Sigma$ and $\langle\Theta\rangle$ the root set generated by $\Theta$. The complementary set $\Pi \backslash\langle\Theta\rangle$ will be denoted as $\langle\Theta\rangle^{\perp}$ and any root in $\langle\Theta\rangle^{\perp}$ will be called a complementary root with respect to $\Theta$. Put $\langle\Theta\rangle^{+}=\langle\Theta\rangle \cap \Pi^{+}$, then, on $\mathfrak{g}$ we have the following decomposition:

$$
\begin{equation*}
\mathfrak{g}=\mathfrak{h} \oplus \sum_{\alpha \in\langle\Theta\rangle^{+}} \mathfrak{g}_{\alpha} \oplus \sum_{\alpha \in\langle\Theta\rangle^{+}} \mathfrak{g}_{-\alpha} \oplus \sum_{\beta \in \Pi^{+} \backslash\langle\Theta\rangle^{+}} \mathfrak{g}_{\beta} \oplus \sum_{\beta \in \Pi^{+} \backslash\langle\Theta\rangle^{+}} \mathfrak{g}_{-\beta}, \tag{3.1}
\end{equation*}
$$

where $\mathfrak{g}_{\alpha}, \alpha \in \Pi$, is the corresponding complex space to $\alpha$. Now let $\mathfrak{p}_{\Theta}$ be the parabolic subalgebra of $\mathfrak{g}$ determined by $\Theta$. Then,

$$
\begin{equation*}
\mathfrak{p}_{\Theta}=\mathfrak{h} \oplus \sum_{\alpha \in\langle\Theta\rangle^{+}} \mathfrak{g}_{\alpha} \oplus \sum_{\alpha \in\langle\Theta\rangle^{+}} \mathfrak{g}_{-\alpha} \oplus \sum_{\beta \in \Pi^{+} \backslash\langle\Theta\rangle^{+}} \mathfrak{g}_{\beta} . \tag{3.2}
\end{equation*}
$$

Thus, the equation (3.1) can be rewritten as

$$
\begin{equation*}
\mathfrak{g}=\mathfrak{p}_{\Theta} \oplus \sum_{\beta \in \Pi^{+} \backslash\langle\Theta\rangle^{+}} \mathfrak{g}_{-\beta} \tag{3.3}
\end{equation*}
$$

The general flag manifold $\mathbb{F}_{\Theta}$ associated with the pair $\{\mathfrak{g}, \Theta\}$ corresponds to the homogeneous space $\mathbb{F}_{\Theta}=G / P_{\Theta}$, where $G$ is the complex Lie group whose Lie algebra is $\mathfrak{g}$ and $P_{\Theta}$ is the normalizer of $\mathfrak{p}_{\Theta}$ in $G$.

Consider the general flag manifold $\mathbb{F}_{\Theta}=G / P_{\Theta}$. Let $\mathfrak{u}$ be a real compact form of $\mathfrak{g}$. Denote for $U$ the connected Lie subgroup of $G$ corresponding to $\mathfrak{u}$. Let $K_{\Theta}=P_{\Theta} \cap U$, by the construction $K_{\Theta}$ is the torus centralizer. Let $\mathfrak{t}_{\Theta}=\mathfrak{u} \cap \mathfrak{p}_{\Theta}$ be the real subalgebra and we will denote by $\mathfrak{t}_{\Theta}^{\mathbb{C}}$ its complexification. We can write,

$$
\begin{equation*}
\mathfrak{t}_{\Theta}^{\mathbb{C}}=\mathfrak{h} \oplus \sum_{\alpha \in\langle\Theta\rangle^{+}} \mathfrak{g}_{\alpha} \oplus \sum_{\alpha \in\langle\Theta\rangle^{+}} \mathfrak{g}_{-\alpha} . \tag{3.4}
\end{equation*}
$$

$U$ acts transitively on $\mathbb{F}_{\Theta}$ and thus we can write $\mathbb{F}_{\Theta}=U / K_{\Theta}$. If $\Theta=\emptyset$, then $\mathbb{F}_{\Theta}=\mathbb{F}$ corresponds to the maximal flag manifold. Otherwise, $\mathbb{F}_{\Theta}$ corresponds to a partial flag manifold. $\mathfrak{u}$ is a real subspace generated by $i \mathfrak{h}_{\mathbb{R}}$, (see Theorem 2.2) and $A_{\alpha}, S_{\alpha}$, with $\alpha \in \Pi \backslash \Theta$, where $A_{\alpha}=X_{\alpha}-X_{-\alpha}$ and $S_{\alpha}=i\left(X_{\alpha}+X_{-\alpha}\right)$. We have $\mathfrak{u}_{\beta}=\mathfrak{u} \cap\left(\mathfrak{g}_{\beta} \oplus \mathfrak{g}_{-\beta}\right), \quad \beta \in \Pi \backslash\langle\Theta\rangle$, and $\mathfrak{q}_{\Theta}=\sum_{\beta \in \Pi \backslash\langle\Theta\rangle} \mathfrak{u}_{\beta}$. Therefore,
(i) $\mathfrak{u}=\mathfrak{t}_{\Theta} \oplus \mathfrak{q}_{\Theta}, \quad \mathfrak{t}_{\Theta} \cap \mathfrak{q}_{\Theta}=\emptyset$;
(ii) $\operatorname{Ad}\left(K_{\Theta}\right) \mathfrak{q}_{\Theta} \subset \mathfrak{q}_{\Theta}$ and this implies $\left[\mathfrak{t}_{\Theta}, \mathfrak{q}_{\Theta}\right] \subset \mathfrak{q}_{\Theta}$.

Conditions (i) and (ii) above guarantee that $\mathbb{F}_{\Theta}$ is a reductive homogeneous space [10].

Now, we denote by $b_{0}$ the origin of $\mathbb{F}_{\Theta}$; here we are thinking $\mathbb{F}_{\Theta}$ like a homogeneous space of $U$. We identify $\mathfrak{q}_{\Theta}=T_{b_{0}}\left(\mathbb{F}_{\Theta}\right)$. This identification is given by $\left\{X \in \mathfrak{q}_{\Theta}\right\} \rightarrow\left\{X_{b_{0}} \in T_{b_{0}}\left(\mathbb{F}_{\Theta}\right)\right\}$, that is, by evaluation of $X \in \mathfrak{q}_{\Theta}$ in $b_{0}$ as a vectorial field on $T_{b_{0}}\left(\mathbb{F}_{\Theta}\right)$. The tangent space of $\mathbb{F}_{\Theta}$ in $b_{0}$ is identified with the subspace $\mathfrak{q}_{\Theta}=\mathfrak{u} \ominus \mathfrak{t}=\sum_{\beta \in \Pi \backslash\langle\Theta\rangle} \mathfrak{u}_{\beta}$, generated by $A_{\alpha}, S_{\alpha}, \alpha \in \Pi \backslash\langle\Theta\rangle$. Similarly, the complexificated tangent space of $\mathbb{F}_{\Theta}$ is identified with $\mathfrak{q}^{\mathbb{C}}=\mathfrak{g} \ominus \mathfrak{h}=\oplus_{\alpha \in \Pi \backslash\langle\Theta\rangle} \mathfrak{g}_{\alpha}$. By the item (ii) above, the action associated to $K_{\Theta}$ leaves $\mathfrak{q}_{\Theta}$ invariant and it splits in irreducible components, invariant by the adjoint action of $K_{\Theta}$ (see [20]). As $\mathfrak{q}_{\Theta}$ is generated by $A_{\alpha}, S_{\alpha}, \alpha \in \Pi \backslash\langle\Theta\rangle$, now we give some properties of these vectors (see [15], section 12.2) that we will use later.

$$
\begin{array}{rlrlrl}
{\left[A_{\alpha}, S_{-\alpha}\right]} & & =i H_{\alpha}, & \left\langle i H_{\alpha}, A_{\beta}\right\rangle & =\left\langle i H_{\alpha}, S_{\beta}\right\rangle=\left\langle A_{\alpha}, S_{\beta}\right\rangle=0 \\
{\left[i H_{\alpha}, S_{\beta}\right]} & =-\beta\left(H_{\alpha}\right) A_{\beta}, & {\left[S_{\alpha}, S_{\beta}\right]} & =-m_{\alpha, \beta} A_{\alpha+\beta}-m_{\alpha,-\beta} A_{\alpha-\beta} \\
{\left[i H_{\alpha}, A_{\beta}\right]} & =\beta\left(H_{\alpha}\right) S_{\beta}, & {\left[A_{\alpha}, A_{\beta}\right]} & =m_{\alpha, \beta} A_{\alpha+\beta}+m_{-\alpha, \beta} A_{\alpha-\beta} \\
\left\langle A_{\alpha}, A_{\alpha}\right\rangle & =\left\langle S_{\alpha}, S_{\alpha}\right\rangle=-2, & {\left[A_{\alpha}, S_{\beta}\right]} & =m_{\alpha, \beta} S_{\alpha+\beta}+m_{\alpha,-\beta} S_{\alpha-\beta} .
\end{array}
$$

## 4. The almost complex manifold $\left(\mathbb{F}_{\Theta}, J^{\Theta}, \Lambda^{\Theta}\right)$

In this Section we will consider $\mathbb{F}_{\Theta}$ to join with an invariant almost complex structure $J^{\Theta}$ and an $U$-invariant riemannian metric $d s_{\Lambda \ominus}^{2}$.

An invariant almost complex structure on $\mathbb{F}_{\Theta}$ is completely determined by its value $J^{\Theta}: \mathfrak{q}_{\Theta} \longrightarrow \mathfrak{q}_{\Theta}$. The map $J^{\Theta}$ satisfies $\left(J^{\Theta}\right)^{2}=-1$ and commutes with the adjoint action of $K_{\Theta}$. We denote with the same letter the real valued structure $J^{\Theta}$ and its complexification to $\mathfrak{q}_{\Theta}{ }^{\mathbb{C}}$.

The invariance of $J^{\Theta}$ entails that $J^{\Theta}\left(\mathfrak{g}_{\alpha}\right)=\mathfrak{g}_{\alpha}$ for all $\alpha \in \Pi \backslash \Theta$. The eigenvalues of $J^{\Theta}$ are $\pm i$ and the eigenvector in $\mathfrak{q}_{\Theta}{ }^{\mathbb{C}}$ are $X_{\alpha}, \alpha \in \Pi$. Hence $J^{\Theta}\left(X_{\alpha}\right)=i \varepsilon_{\alpha} X_{\alpha}$, with $\varepsilon_{\alpha}= \pm 1$ and satisfying $\varepsilon_{-\alpha}=-\varepsilon_{\alpha}$. As usual, eigenvectors associated to $+i$ are namely the type ( 1,0 ), while $-i$-eigenvectors are namely the type $(0,1)$. An invariant almost complex structure on $\mathbb{F}_{\Theta}$ is completely prescribed by a set of signs $\left\{\varepsilon_{\alpha}\right\}_{\alpha \in \Pi \backslash \Theta}$, with $\varepsilon_{-\alpha}=-\varepsilon_{\alpha}$. In the sequel we abuse the notation to identify the invariant structure on $\mathbb{F}_{\Theta}$ with $J^{\Theta}=\left\{\varepsilon_{\alpha}\right\}_{\alpha \in \Pi}$.

An $U$-invariant riemannian metric $d s_{\Lambda \Theta}^{2}$ on $\mathbb{F}_{\Theta}$ is completely determined by its values in the origin, that is, by an inner product $(\cdot, \cdot)$ in $\mathfrak{q}_{\Theta}$, invariant under the action associated to $K_{\Theta}([3],[19],[20])$. Such inner product has the form $(X, Y)_{\Lambda^{\Theta}}=-\left\langle\Lambda^{\Theta} \circ X, Y\right\rangle$, with $\Lambda^{\Theta}: \mathfrak{q}_{\Theta} \rightarrow \mathfrak{q}_{\Theta}$ positive definite with respect to the Cartan-Killing form and $\circ$ is the Hadamard product or product term by term. The inner product $(\cdot, \cdot)_{\Lambda \ominus}$ admits a natural extension to a bilinear symmetric form on $\mathfrak{q}_{\Theta}^{\mathbb{C}}$ and we use the same notation $(\cdot, \cdot)_{\Lambda^{\ominus}}$ to this extension. Similarly, to the corresponding complexified form $\Lambda^{\Theta}$ we maintain the same notation too. $K_{\Theta}$-invariance of $(\cdot, \cdot)_{\Lambda^{\ominus}}$ is equivalent to affirm that the Weyl base is a complex base of eigenvectors for the action of $\Lambda^{\Theta}$, that is, in $\mathfrak{q}_{\Theta}^{\mathbb{C}}$ we have

$$
\begin{equation*}
\Lambda^{\Theta} X_{\alpha}=\lambda_{\alpha}^{\Theta} X_{\alpha} \tag{4.1}
\end{equation*}
$$

with $\lambda_{\alpha}^{\Theta}=\lambda_{-\alpha}^{\Theta}>0$. for $\alpha \in \Pi \backslash\langle\Theta\rangle$.
For the real algebra $\mathfrak{q}_{\Theta}$, the elements of the canonical base $A_{\alpha}, S_{\alpha}$, with $\alpha \in \Pi \backslash\langle\Theta\rangle$, are eigenvectors to the same eigenvalue $\lambda_{\alpha}^{\Theta}$. In the sequel we will use $\Lambda^{\Theta}$ as synonymous of $d s_{\Lambda^{\ominus}}^{2}$ and in the case of the maximal flag manifold $\mathbb{F}$ we will use only $\Lambda$.

Definition 4.1. Let $J^{\Theta}$ be an invariant almost complex structure on $\mathbb{F}_{\Theta}$. A triple of roots $\alpha, \beta, \gamma$ with $\alpha+\beta+\gamma=0$ is said to be a $\{0,3\}$-triple if $\varepsilon_{\alpha}=$ $\varepsilon_{\beta}=\varepsilon_{\gamma}$ and a $\{1,2\}$-triple otherwise.

Recall that an almost hermitian manifold is said to be Kähler if $d \Omega(X, Y, Z)=0$, for all vectors $X, Y, Z$ in its tangent space, and $(1,2)$-symplectic if $d \Omega(X, Y, Z)=0$, when one of the vectors $X, Y, Z$ is type $(1,0)$ and the other two are type $(0,1)$. Here $\Omega$ is the Kähler form which is given by

$$
\Omega(X, Y)=d s_{\Lambda^{\ominus}}^{2}(X, J Y)=-\left\langle\Lambda^{\Theta} \circ X, J Y\right\rangle
$$

In the Weyl basis we have $\Omega\left(X_{\alpha}, X_{\beta}\right)=\left(X_{\alpha}, J X_{\beta}\right)_{\Lambda}=-\left\langle\Lambda X_{\alpha}, J X_{\beta}\right\rangle$, that is,

$$
\Omega\left(X_{\alpha}, X_{\beta}\right)= \begin{cases}i \varepsilon_{\alpha} \lambda_{\alpha}, & \text { if } \beta=-\alpha \\ 0, & \text { otherwise }\end{cases}
$$

for all $\alpha, \beta \in \Pi \backslash\langle\Theta\rangle$.

## 5. Riemannian connection on $\left(\mathbb{F}_{\Theta}, \Lambda^{\Theta}\right)$

Since $\mathbb{F}_{\Theta}$ is a naturally reductive homogeneous space, lets present a known result about this kind of spaces that will be very useful to calculate the riemannian connection in $\mathbb{F}_{\Theta}$.
Theorem 5.1. [10] Let $M=G / H$ be a reductive homogeneous space with an $\operatorname{ad}(H)$-invariant decomposition $\mathfrak{g}=\mathfrak{h} \oplus \mathfrak{m}$ and an $\operatorname{ad}(H)$-invariant nondegenerate symmetric bilinear form $B$ on $\mathfrak{m}$. Let $g$ be the $G$-invariant metric corresponding to $B$. Then
(1) The riemannian connection for $g$ is given by

$$
\nabla_{X}^{\mathfrak{m}} Y=\frac{1}{2}[X, Y]_{\mathfrak{m}}+U(X, Y)
$$

where $U(X, Y)$ is the symmetric bilinear mapping on $\mathfrak{m} \times \mathfrak{m}$ into $\mathfrak{m}$, defined by

$$
2 B(U(X, Y), Z)=B\left(X,[Z, Y]_{\mathfrak{m}}\right)+B\left([Z, X]_{\mathfrak{m}}, Y\right)
$$

for all $X, Y, Z \in \mathfrak{m}$.
(2) The riemannian connection for $g$ matches with the natural torsion-free connection if, and only if, $B$ satisfies

$$
B\left(X,[Z, Y]_{\mathfrak{m}}\right)+B\left([Z, X]_{\mathfrak{m}}, Y\right)=0, \quad \text { for } X, Y, Z \in \mathfrak{m}
$$

Here we are interested in a symmetric bilinear application $U: \mathfrak{q}_{\Theta} \times \mathfrak{q}_{\Theta} \rightarrow$ $\mathfrak{q}_{\Theta}$ satisfying $2 \Lambda^{\Theta}(U(X, Y), Z)=\Lambda^{\Theta}\left(X,[Y, Z]_{\mathfrak{q}_{\Theta}}\right)+\Lambda^{\Theta}\left([Z, X]_{\mathfrak{q}_{\Theta}}, Y\right)$, for all $X, Y, Z \in \mathfrak{q}_{\Theta} ;$ or $2\left\langle\Lambda^{\Theta} \circ U(X, Y), Z\right\rangle=\left\langle\Lambda^{\Theta} \circ X,[Y, Z]_{\mathfrak{q}_{\ominus}}\right\rangle+\left\langle[Z, X]_{\mathfrak{q}_{\ominus}}, \Lambda^{\Theta} \circ Y\right\rangle$. Since

$$
\begin{equation*}
\left\langle[X, Y]_{\mathfrak{q}_{\ominus}}, Z\right\rangle=\left\langle X,[Y, Z]_{\mathfrak{q}_{\ominus}}\right\rangle \tag{5.1}
\end{equation*}
$$

we have,

$$
2\left\langle\Lambda^{\Theta} \circ U(X, Y), Z\right\rangle=-\left\langle\left[\Lambda^{\Theta} \circ X, Y\right]_{\mathfrak{q}_{\ominus}}, Z\right\rangle+\left\langle\left[X, \Lambda^{\Theta} \circ Y\right]_{\mathfrak{q}_{\ominus}}, Z\right\rangle
$$

and

$$
\begin{equation*}
2 \Lambda^{\Theta} \circ U(X, Y)=\left[X, \Lambda^{\Theta} \circ Y\right]_{\mathfrak{q}_{\Theta}}-\left[\Lambda^{\Theta} \circ X, Y\right]_{\mathfrak{q}_{\Theta}} \tag{5.2}
\end{equation*}
$$

Using again Theorem 5.1 the riemannian connection $\nabla$ in $\left(\mathbb{F}_{\Theta}, \Lambda^{\Theta}\right)$ is given by

$$
\begin{equation*}
2 \nabla_{X} Y=[X, Y]_{\mathfrak{q}_{\Theta}}+2 U(X, Y) \tag{5.3}
\end{equation*}
$$

then

$$
\begin{equation*}
2 \nabla_{X} Y=[X, Y]_{\mathfrak{q}_{\Theta}}+\Lambda^{\Theta}{ }^{-1} \circ\left(\left[X, \Lambda^{\Theta} Y\right]_{\mathfrak{q}_{\Theta}}-\left[\Lambda^{\Theta} X, Y\right]_{\mathfrak{q}_{\Theta}}\right) \tag{5.4}
\end{equation*}
$$

with $X, Y \in \mathfrak{q}_{\Theta}$ and $\left(\Lambda^{\Theta}\right)^{-1}$ the inverse of $\Lambda^{\Theta}$ with respect to the Hadamard product. Note that $\left(\Lambda^{\Theta}\right)^{-1}=\left(\left(\lambda_{\alpha}^{\Theta}\right)^{-1}\right)_{\alpha \in \Pi \backslash\langle\Theta\rangle}$. Finally, in the Weyl basis we have

$$
2 U\left(X_{\alpha}, X_{\beta}\right)= \begin{cases}\frac{\lambda_{\beta}^{\Theta}-\lambda_{\alpha}^{\Theta}}{\lambda_{\alpha+\beta}^{\Theta}}\left[X_{\alpha}, X_{\beta}\right], & \text { if } \alpha+\beta \in \Pi \backslash\langle\Theta\rangle, \\ 0, & \text { otherwise }\end{cases}
$$

Therefore in the Weyl basis, the riemannian connection is characterized by the following proposition.

Proposition 5.2. Consider $\left(\mathbb{F}_{\Theta}, \Lambda^{\Theta}\right)$, $\alpha, \beta, \alpha+\beta \in \Pi \backslash\langle\Theta\rangle$, and $X_{\alpha}, X_{\beta}$, $X_{\alpha+\beta} \in \mathfrak{q}_{\Theta}$, then

$$
\begin{equation*}
\nabla_{X_{\alpha}} X_{\beta}=\frac{\lambda_{\alpha+\beta}^{\Theta}+\lambda_{\beta}^{\Theta}-\lambda_{\alpha}^{\Theta}}{2 \lambda_{\alpha+\beta}^{\Theta}}\left[X_{\alpha}, X_{\beta}\right] \tag{5.5}
\end{equation*}
$$

Proof. Using equation (5.3), item 5 in Theorem 2.1, and equation (4.1) we obtain

$$
\begin{aligned}
2 \nabla_{X_{\alpha}} X_{\beta} & =\left[X_{\alpha}, X_{\beta}\right]_{\mathfrak{q}_{\Theta}}+2 U\left(X_{\alpha}, X_{\beta}\right), \\
& =m_{\alpha, \beta} X_{\alpha+\beta}+\frac{\lambda_{\beta}^{\Theta}-\lambda_{\alpha}^{\Theta}}{\lambda_{\alpha+\beta}^{\Theta}}\left[X_{\alpha}, X_{\beta}\right] \\
& =\frac{\lambda_{\alpha+\beta}^{\Theta}+\lambda_{\beta}^{\Theta}-\lambda_{\alpha}^{\Theta}}{\lambda_{\alpha+\beta}^{\Theta}}\left[X_{\alpha}, X_{\beta}\right] .
\end{aligned}
$$

## 6. Generalized flag manifold and curvature

Since the beginning our main objective was to look for a handy way to calculate the riemannian connection on flag manifolds, Proposition 5.2 gives us (5.5) which is an easy expression to calculate the riemannian connection on $\mathbb{F}_{\Theta}=$ $G / P_{\Theta}=U / K_{\Theta}$. Now we use it in order to understand, or at least to show the behavior of some type of curvatures on $\mathbb{F}_{\Theta}$.

For reductive homogenous spaces, again [10] provides an expression for the curvature tensor, using it jointly with the equation (5.4), in $b_{0}$ we have

$$
\begin{equation*}
R(X, Y)_{b_{0}}=\left[\nabla^{\mathfrak{q} \Theta} X, \nabla^{\mathfrak{q} \ominus} Y\right]-\nabla[X, Y]_{\mathfrak{q}_{\ominus}}-a d\left([X, Y]_{\mathfrak{t}_{\Theta}}\right), \tag{6.1}
\end{equation*}
$$

for all $X, Y \in \mathfrak{q}_{\Theta}$, with $\mathfrak{q}_{\Theta}$ and $\mathfrak{t}_{\Theta}$ as in (3.4). Here $\nabla^{\mathfrak{q} \Theta}$ represents the riemannian connection on $\mathfrak{q}_{\Theta}$ and []$_{\mathfrak{q}_{\Theta}}$, [ $]_{\mathfrak{t}_{\Theta}}$ represent the bracket projection on the respective spaces.

We know that (see [9]) for each plane generated by the vectors $X, Y$ in the tangent space, the sectional curvature of the plane is defined by

$$
\begin{equation*}
K(X, Y)=\Lambda^{\Theta}(R(X, Y) X, Y) \tag{6.2}
\end{equation*}
$$

Thus, applying the equations (6.2) and (6.1) we have

$$
\begin{equation*}
K(X, Y)=\Lambda^{\Theta}\left(\nabla_{X} \nabla_{Y} X-\nabla_{Y} \nabla_{X} X-\nabla_{[X, Y]_{\mathfrak{q}_{\Theta}}} X-\left[[X, Y]_{\mathfrak{t}_{\Theta}}, X\right], Y\right) . \tag{6.3}
\end{equation*}
$$

Now suppose that $[X, Y]_{\mathfrak{t}_{\Theta}}=0$. Using (6.3), (5.4) and the invariance of $\langle\cdot, \cdot \cdot\rangle$ (5.1) we have

$$
\begin{align*}
K(X, Y)= & \Lambda^{\Theta}\left(\nabla_{X} \nabla_{Y} X, Y\right)-\Lambda^{\Theta}\left(\nabla_{Y} \nabla_{X} X, Y\right)-\Lambda^{\Theta}\left(\nabla_{[X, Y]} X, Y\right) \\
= & \Lambda^{\Theta}\left(\frac{1}{2}\left[X, \nabla_{Y} X\right], Y\right)+\Lambda^{\Theta}\left(\frac{1}{2}\left(\Lambda^{\Theta}\right)^{-1}\left[X, \Lambda^{\Theta} \nabla_{Y} X\right], Y\right) \\
& -\Lambda^{\Theta}\left(\frac{1}{2}\left(\Lambda^{\Theta}\right)^{-1}\left[\Lambda^{\Theta} X, \nabla_{Y} X\right], Y\right)-\Lambda^{\Theta}\left(\frac{1}{2}[[X, Y], X], Y\right)+ \\
& -\frac{1}{2}\left(\Lambda^{\Theta}\right)^{-1}\left[[X, Y], \Lambda^{\Theta} X\right], y+\Lambda^{\Theta}\left(\frac{1}{2}\left(\Lambda^{\Theta}\right)^{-1}\left[\Lambda^{\Theta}[X, Y], X\right], Y\right) \\
= & -\left\{\frac{1}{2}\left\langle\left[X, \nabla_{Y} X\right], \Lambda^{\Theta} Y\right\rangle+\frac{1}{2}\left\langle\left[X, \Lambda^{\Theta} \nabla_{Y} X\right], Y\right\rangle-\frac{1}{2}\left\langle\left[\Lambda^{\ominus} X, \nabla_{Y} X\right], Y\right\rangle\right. \\
& \left.-\frac{1}{2}\left\langle[[X, Y], X], \Lambda^{\Theta} Y\right\rangle-\frac{1}{2}\left\langle\left[[X, Y], \Lambda^{\Theta} X\right], Y\right\rangle \frac{1}{2}\left\langle\left[\Lambda^{\Theta}[X, Y], X\right], Y\right\rangle\right\} \\
= & -\left\{-\frac{1}{2}\left\langle\nabla_{Y} X,\left[X, \Lambda^{\Theta} Y\right]\right\rangle-\frac{1}{2}\left\langle\Lambda^{\Theta} \nabla_{Y} X,[X, Y]\right\rangle+\frac{1}{2}\left\langle\nabla_{Y} X,\left[\Lambda^{\Theta} X, Y\right]\right\rangle\right. \\
& +\frac{1}{2}\left\langle\nabla_{X} X,\left[Y, \Lambda^{\Theta} Y\right]\right\rangle-\frac{1}{2}\left\langle\nabla_{X} X,[Y, Y]\right\rangle-\frac{1}{2}\left\langle\nabla_{X} X,\left[\Lambda^{\Theta} Y, Y\right]\right\rangle \\
& \left.-\frac{1}{2}\left\langle[X, Y],\left[X, \Lambda^{\Theta} Y\right]\right\rangle-\frac{1}{2}\left\langle[X, Y],\left[\Lambda^{\Theta} X, Y\right]\right\rangle+\frac{1}{2}\left\langle\Lambda^{\Theta}[X, Y],[X, Y]\right\rangle\right\} \\
= & \frac{1}{2}\left\langle[X, Y],\left[X, \Lambda^{\Theta} Y\right]\right\rangle-\frac{1}{4}\left\langle\left(\Lambda^{\Theta}\right)^{-1}\left[\Lambda^{\Theta} X, Y\right],\left[X, \Lambda^{\Theta} Y\right]\right\rangle \\
& +\frac{1}{4}\left\langle\left(\Lambda^{\Theta}\right)^{-1}\left[X, \Lambda^{\Theta} Y\right],\left[X, \Lambda^{\Theta} Y\right]\right\rangle-\frac{3}{4}\left\langle\Lambda^{\Theta}[X, Y],[X, Y]\right\rangle \\
& +\frac{1}{2}\left\langle\left[\Lambda^{\Theta} X, Y\right],[X, Y]\right\rangle+\frac{1}{4}\left\langle\left(\Lambda^{\Theta}\right)^{-1}\left[\Lambda^{\Theta} X, Y\right],\left[\Lambda^{\Theta} X, Y\right]\right\rangle \\
& -\frac{1}{4}\left\langle\left(\Lambda^{\Theta}\right)^{-1}\left[X, \Lambda^{\Theta} Y\right],\left[\Lambda^{\Theta} X, Y\right]\right\rangle . \tag{6.4}
\end{align*}
$$

Proposition 6.1. Consider the maximal flag manifold $\mathbb{F}$, and the basic vectors $A_{\alpha}, S_{\alpha}, \alpha \in \Pi$. Then
(i) $K\left(A_{\alpha}, S_{\beta}\right)=K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)=-\xi_{\alpha, \beta} m_{\alpha, \beta}^{2}+\xi_{-\alpha, \beta} m_{-\alpha, \beta}^{2}$, where

$$
\begin{equation*}
\xi_{\alpha, \beta}=\lambda_{\alpha}+\lambda_{\beta}+\frac{\lambda_{\alpha}^{2}+\lambda_{\beta}^{2}-2 \lambda_{\alpha} \lambda_{\beta}}{2\left(\lambda_{\alpha+\beta}\right)}-\frac{3 \lambda_{\alpha+\beta}}{2} \tag{6.5}
\end{equation*}
$$

(ii) $K\left(A_{\alpha}, S_{-\alpha}\right)=-4 \lambda_{\alpha} \alpha\left(H_{\alpha}\right)$.

Proof.
(i) It is immediately obtained using (6.4) and (3.5) and the property $m_{\alpha,-\beta}^{2}=m_{-\alpha, \beta}^{2}$.
(ii) On the maximal flag manifold, $\mathfrak{t}=\mathfrak{h}$ and the only case where $[X, Y]_{\mathfrak{h}} \neq$ 0 is when $X=A_{\alpha}$ and $Y=S_{-\alpha}$. Then, $\left[A_{\alpha}, S_{-\alpha}\right]=2 i H_{\alpha}$ and we
obtain

$$
\begin{align*}
K\left(A_{\alpha}, S_{-\alpha}\right)= & \Lambda\left(\nabla_{A_{\alpha}} \nabla_{S_{-\alpha}} A_{\alpha}, S_{-\alpha}\right)-\Lambda\left(\nabla_{S_{-\alpha}} \nabla_{A_{\alpha}} A_{\alpha}, S_{-\alpha}\right)+ \\
& -\Lambda\left(\nabla_{\left[A_{\alpha}, S_{-\alpha}\right]} A_{\alpha}, S_{-\alpha}\right)-\Lambda\left(\Lambda\left(\left[A_{\alpha}, S_{-\alpha}\right]_{\mathfrak{h}}\right) A_{\alpha}, S_{-\alpha}\right), \\
= & \Lambda\left(\frac{1}{2}\left[A_{\alpha}, \nabla_{S_{-\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right)+\Lambda\left(\frac{1}{2} \Lambda^{-1}\left[A_{\alpha}, \Lambda \nabla_{S_{-\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right)+ \\
& -\Lambda\left(\frac{1}{2} \Lambda^{-1}\left[\Lambda A_{\alpha}, \nabla_{S_{-\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right)-\Lambda\left(\frac{1}{2}\left[S_{-\alpha}, \nabla_{A_{\alpha}} A_{\alpha}\right], S_{-\alpha}\right)+ \\
& -\Lambda\left(\frac{1}{2} \Lambda^{-1}\left[S_{-\alpha}, \Lambda \nabla_{A_{\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right)+ \\
& +\Lambda\left(\frac{1}{2} \Lambda \Lambda^{-1}\left[\Lambda A_{\alpha}, \nabla_{A_{\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right)+ \\
& -d s_{\Lambda}^{2}\left(\left[\left[A_{\alpha}, S_{-\alpha}\right]_{\mathfrak{h}}, A_{\alpha}\right], S_{-\alpha}\right), \\
= & -\left\{\frac{\lambda_{\alpha}}{2}\left\langle\left[A_{\alpha}, \nabla_{S_{-\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right\rangle+\frac{1}{2}\left\langle\left[A_{\alpha}, \Lambda \nabla_{S_{-\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right\rangle+\right. \\
& -\frac{1}{2}\left\langle\left[\Lambda A_{\alpha}, \nabla_{S_{-\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right\rangle-\frac{\lambda_{\alpha}}{2}\left\langle\left[S_{-\alpha}, \nabla_{A_{\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right\rangle+ \\
& \left.-\frac{1}{2}\left\langle\left[S_{-\alpha}, \Lambda \nabla_{A_{\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right\rangle+\frac{1}{2}\left\langle\left[\Lambda A_{\alpha}, \nabla_{A_{\alpha}} A_{\alpha}\right]_{\mathfrak{q}}, S_{-\alpha}\right\rangle\right\}+ \\
& \lambda_{\alpha}\left\langle\left[2 i H_{\alpha}, A_{\alpha}\right], S_{-\alpha}\right\rangle, \\
= & -\left\{-\frac{\lambda_{\alpha}}{2}\left\langle\nabla_{S_{-\alpha}} A_{\alpha},\left[A_{\alpha}, S_{-\alpha}\right]_{\mathfrak{q}}\right\rangle-\frac{1}{2}\left\langle\Lambda \nabla_{S_{-\alpha}} A_{\alpha},\left[A_{\alpha}, S_{-\alpha}\right]_{\mathfrak{q}}\right\rangle+\right. \\
& +\frac{1}{2}\left\langle\nabla_{S_{-\alpha}} A_{\alpha},\left[\Lambda A_{\alpha}, S_{-\alpha}\right]_{\mathfrak{q}}\right\rangle+\frac{\lambda_{\alpha}}{2}\left\langle\nabla_{A_{\alpha}} A_{\alpha},\left[S_{-\alpha}, S_{-\alpha}\right]_{\mathfrak{q}}\right\rangle+ \\
& \left.+\frac{1}{2}\left\langle\Lambda \nabla_{A_{\alpha}} A_{\alpha},\left[S_{-\alpha}, S_{-\alpha}\right]_{\mathfrak{q}}\right\rangle-\frac{1}{2}\left\langle\nabla_{A_{\alpha}} A_{\alpha},\left[\Lambda A_{\alpha}, S_{-\alpha}\right]_{\mathfrak{q}}\right\rangle\right\}+ \\
& +2 \lambda_{\alpha}\left\langle\alpha\left(H_{\alpha}\right) S_{-\alpha}, S_{-\alpha}\right\rangle, \\
= & -4 \lambda_{\alpha} \alpha\left(H_{\alpha}\right) . \tag{6.6}
\end{align*}
$$

Note that in the last case in the proposition above $K\left(A_{\alpha}, S_{-\alpha}\right)<0$, since $\alpha\left(H_{\alpha}\right)$ is a positive rational.

Now, lets consider $(\mathbb{F}, J, \Lambda)$ to be an almost Hermitian maximal flag manifold, and assume that $\alpha, \beta \in \Sigma$, then $\pm(\alpha-\beta)$ is not in $\Pi$ and (6.5) is reduced to

$$
K\left(A_{\alpha}, S_{\beta}\right)=K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)=-\xi_{\alpha, \beta} m_{\alpha, \beta}^{2}
$$

Remark 6.1. Now assume that $J$ is integrable, $(\mathbb{F}, J, \Lambda)$ is Kähler [17] and all zero-sum triple $\{\alpha, \beta,-(\alpha+\beta)\}$ must be of the type $\{1,2\}$. Here we have the following cases
(1) If $\lambda_{\alpha}=\lambda_{\beta}+\lambda_{\alpha+\beta}$, we have

$$
K\left(A_{\alpha}, S_{\beta}\right)=K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)=-2 \lambda_{\beta}\left(m_{\alpha, \beta}\right)^{2}<0
$$

(2) If $\lambda_{\beta}=\lambda_{\alpha}+\lambda_{\alpha+\beta}$, we have

$$
K\left(A_{\alpha}, S_{\beta}\right)=K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)=-2 \lambda_{\alpha}\left(m_{\alpha, \beta}\right)^{2}<0
$$

(3) If $\lambda_{\alpha}+\lambda_{\beta}=\lambda_{\alpha+\beta}$, we have

$$
K\left(A_{\alpha}, S_{\beta}\right)=K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)=\frac{2 \lambda_{\alpha} \lambda_{\beta}}{\lambda_{\alpha}+\lambda_{\beta}}\left(m_{\alpha, \beta}\right)^{2}>0
$$

(4) If $\lambda_{\alpha+\beta}=2 \lambda_{\alpha}$, we have

$$
K\left(A_{\alpha}, S_{\beta}\right)=K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)=\lambda_{\alpha}\left(m_{\alpha, \beta}\right)^{2}>0
$$

Now, when $\alpha-\beta$ is also a root, we have that $\{\alpha, \beta,-(\alpha+\beta)\},\{\beta,-\alpha, \alpha-\beta\}$ are $\{1,2\}$-triples, then we have the following cases:
(1) If $\lambda_{\alpha}=\lambda_{\beta}+\lambda_{\alpha+\beta}$, then $\lambda_{\alpha-\beta}=\lambda_{\alpha}+\lambda_{\beta}$ and

$$
\begin{aligned}
K\left(A_{\alpha}, S_{\beta}\right) & =K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right) \\
& =-2 \lambda_{\beta}\left\{\left(m_{\alpha, \beta}\right)^{2}-\frac{\lambda_{\alpha}}{\lambda_{\alpha}+\lambda_{\beta}}\left(m_{\alpha,-\beta}\right)^{2}\right\} .
\end{aligned}
$$

(2) If $\lambda_{\beta}=\lambda_{\alpha}+\lambda_{\alpha+\beta}$, then $\lambda_{\alpha-\beta}=\lambda_{\alpha}+\lambda_{\beta}$ and

$$
\begin{aligned}
K\left(A_{\alpha}, S_{\beta}\right) & =K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)= \\
& =-2 \lambda_{\alpha}\left\{\left(m_{\alpha, \beta}\right)^{2}-\frac{\lambda_{\beta}}{\lambda_{\alpha}+\lambda_{\beta}}\left(m_{\alpha,-\beta}\right)^{2}\right\} .
\end{aligned}
$$

(3) If $\lambda_{\alpha+\beta}=\lambda_{\alpha}+\lambda_{\beta}$, then we have two cases:

- If $\lambda_{\alpha}=\lambda_{\beta}+\lambda_{\alpha-\beta}$, we have

$$
\begin{aligned}
K\left(A_{\alpha}, S_{\beta}\right) & =K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)= \\
& =-2 \lambda_{\beta}\left\{-\frac{\lambda_{\alpha}}{\lambda_{\alpha}+\lambda_{\beta}}\left(m_{\alpha, \beta}\right)^{2}+\left(m_{\alpha,-\beta}\right)^{2}\right\} .
\end{aligned}
$$

- If $\lambda_{\beta}=\lambda_{\alpha}+\lambda_{\alpha-\beta}$, we have

$$
\begin{aligned}
K\left(A_{\alpha}, S_{\beta}\right) & =K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)= \\
& =-2 \lambda_{\alpha}\left\{-\frac{\lambda_{\beta}}{\lambda_{\alpha}+\lambda_{\beta}}\left(m_{\alpha, \beta}\right)^{2}+\left(m_{\alpha,-\beta}\right)^{2}\right\} .
\end{aligned}
$$

Example 6.1. Let us consider the invariant case $(\mathbb{F}(3), J, \Lambda)$ to be Kähler, in this case

$$
\Lambda=\left(\begin{array}{ccc}
0 & \lambda_{\alpha} & 2 \lambda_{\alpha} \\
\lambda_{\alpha} & 0 & \lambda_{\alpha} \\
2 \lambda_{\alpha} & \lambda_{\alpha} & 0
\end{array}\right)
$$

As $\alpha+2 \beta, 2 \alpha+\beta$ are not roots we have

$$
\begin{aligned}
K\left(A_{\alpha}, S_{\beta}\right) & =K\left(S_{\alpha}, S_{\beta}\right)=K\left(A_{\alpha}, A_{\beta}\right)=\lambda_{\alpha}\left(m_{\alpha, \beta}\right)^{2} \\
K\left(A_{\alpha}, A_{\alpha+\beta}\right) & =K\left(A_{\alpha}, S_{\alpha+\beta}\right)=K\left(S_{\alpha}, A_{\alpha+\beta}\right)= \\
& =K\left(S_{\alpha}, A_{\alpha+\beta}\right)=K\left(S_{\beta}, A_{\alpha+\beta}\right)=K\left(S_{\beta}, A_{\alpha+\beta}\right)=0 \\
K\left(A_{\alpha}, S_{\alpha}\right) & =K\left(A_{\beta}, S_{\beta}\right)=4 \lambda_{\alpha} \alpha\left(H_{\alpha}\right)>0 .
\end{aligned}
$$

Thus the scalar curvature of $\mathbb{F}(3)$ is $3 \lambda_{\alpha}\left(m_{\alpha, \beta}\right)^{2}+8 \lambda_{\alpha} \alpha\left(H_{\alpha}\right)>0$. So we have that the Ricci curvature $\operatorname{Ric}\left(A_{\alpha+\beta}\right)=\operatorname{Ric}\left(S_{\alpha+\beta}\right)=0$ and $\operatorname{Ric}\left(A_{\alpha}\right)=$ $\operatorname{Ric}\left(A_{\beta}\right)=\operatorname{Ric}\left(S_{\alpha}\right)=\operatorname{Ric}\left(S_{\beta}\right)=2 \lambda_{\alpha}\left(m_{\alpha, \beta}\right)^{2}+4 \lambda_{\alpha} \alpha\left(H_{\alpha}\right)>0$. In $\mathbb{F}(n)$ is the only case where Ric $>0$.

In the next sections we will study some type of curvatures, such as: holomorphic bisectional curvature and sectional Kälherian curvature on ( $\mathbb{F}, J, \Lambda$ ) in order to understand, through the possible values of these curvatures, some aspects of its geometry and its topology, (see for example [10], [18], [6], [16]).

## 7. Holomorphic bisectional curvature

Let $(N, J, g)$ be a Hermitian riemannian manifold. $\operatorname{HBRiem}^{N}(X, Y)$ denotes the holomorphic bisectional curvature of $N$, given by the following equation (see [10])

$$
\operatorname{HBRiem}^{N}(X, Y)=g\left(R^{N}(X, J X) Y, J Y\right)
$$

where $R^{N}$ is the curvature tensor in $N$. In our case, $(\mathbb{F}, J, \Lambda)$, since $J$ is an endomorphism it is easy to show that on basic vectors $A_{\alpha}, S_{\beta}$ we have

$$
J\left(A_{\alpha}\right)=\varepsilon_{\alpha} S_{\alpha}, \quad J\left(S_{\alpha}\right)=-\varepsilon_{\alpha} A_{\alpha} .
$$

Then,

$$
\begin{aligned}
\operatorname{HBRiem}\left(A_{\alpha}, S_{\beta}\right) & =\Lambda\left(R\left(A_{\alpha}, J\left(A_{\alpha}\right) S_{\beta}, J\left(S_{\beta}\right)\right),\right. \\
& =-\Lambda\left(R\left(A_{\alpha}, \varepsilon_{\alpha} S_{\alpha}\right) S_{\beta}, \varepsilon_{\beta} A_{\beta}\right), \\
& =-\varepsilon_{\alpha} \varepsilon_{\beta} \Lambda\left(R\left(A_{\alpha}, S_{\alpha}\right) S_{\beta}, A_{\beta}\right) . \\
\operatorname{HBRiem}\left(A_{\alpha}, A_{\beta}\right) & =\Lambda\left(R\left(A_{\alpha}, J\left(A_{\alpha}\right)\right) A_{\beta}, J\left(A_{\beta}\right)\right), \\
& =\Lambda\left(R\left(A_{\alpha}, \varepsilon_{\alpha} S_{\alpha}\right) A_{\beta}, \varepsilon_{\beta} S_{\beta}\right), \\
& =\varepsilon_{\alpha} \varepsilon_{\beta} \Lambda\left(R\left(A_{\alpha}, S_{\alpha}\right) A_{\beta}, S_{\beta}\right), \\
& =-\varepsilon_{\alpha} \varepsilon_{\beta} \Lambda\left(R\left(A_{\alpha}, S_{\alpha}\right) S_{\beta}, A_{\beta}\right) . \\
\operatorname{HBRiem}\left(S_{\alpha}, S_{\beta}\right) & =\Lambda\left(R\left(S_{\alpha}, J\left(S_{\alpha}\right)\right) S_{\beta}, J\left(S_{\beta}\right)\right), \\
& =\Lambda\left(R\left(S_{\alpha},-\varepsilon_{\alpha} A_{\alpha}\right) A_{\beta},-\varepsilon_{\beta} A_{\beta}\right), \\
& =\varepsilon_{\alpha} \varepsilon_{\beta} \Lambda\left(R\left(S_{\alpha}, A_{\alpha}\right) S_{\beta}, A_{\beta}\right), \\
& =-\varepsilon_{\alpha} \varepsilon_{\beta} \Lambda\left(R\left(A_{\alpha}, S_{\alpha}\right) S_{\beta}, A_{\beta}\right) .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
\operatorname{HBRiem}\left(A_{\alpha}, S_{\beta}\right) & =\operatorname{HBRiem}\left(A_{\alpha}, A_{\beta}\right)=\operatorname{HBRiem}\left(S_{\alpha}, S_{\beta}\right)= \\
& =-\varepsilon_{\alpha} \varepsilon_{\beta}\left(m_{\alpha, \beta}^{2}\left(2 \lambda_{\beta}-2 \lambda_{\alpha}+\lambda_{\alpha+\beta}\right)-\frac{\left(\lambda_{\alpha}-\lambda_{\beta}\right)^{2}}{\lambda_{\alpha-\beta}} m_{\alpha,-\beta}^{2}\right)
\end{aligned}
$$

while,

$$
\begin{aligned}
\operatorname{HBRiem}\left(A_{\alpha}, S_{-\alpha}\right) & =\Lambda\left(R\left(A_{\alpha}, J\left(A_{\alpha}\right)\right) S_{-\alpha}, J\left(S_{-\alpha}\right)\right) \\
& =\varepsilon_{\alpha}^{2} \Lambda\left(R\left(A_{\alpha}, S_{-\alpha}\right) S_{-\alpha}, A_{\alpha}\right) \\
& =-\Lambda\left(R\left(A_{\alpha}, S_{-\alpha}\right) A_{\alpha}, S_{-\alpha}\right) \\
& =-K\left(A_{\alpha}, S_{-\alpha}\right) \\
& =4 \alpha\left(H_{\alpha}\right) \lambda_{\alpha}>0 .
\end{aligned}
$$

Now suposse that $(\mathbb{F}, J, \Lambda)$ is Kähler and take $\alpha, \beta \in \Sigma$, then $\alpha-\beta$ is not root; therefore,

$$
\operatorname{HBRiem}\left(A_{\alpha}, S_{\beta}\right)=-\varepsilon_{\alpha} \varepsilon_{\beta} m_{\alpha, \beta}^{2}\left(2 \lambda_{\beta}-2 \lambda_{\alpha}+\lambda_{\alpha+\beta}\right) .
$$

If $\{\alpha, \beta,-(\alpha+\beta)\}$ is a $\{1,2\}$-triple the only interesting case is when $\lambda_{\alpha+\beta}=$ $2 \lambda_{\alpha}$, then,

$$
\operatorname{HBRiem}\left(A_{\alpha}, S_{\beta}\right)=-2 m_{\alpha, \beta}^{2} \lambda_{\alpha}<0
$$

The previous calculations jointly with a result due to Siu and Yau [18] implies that if $(\mathbb{F}, \Lambda, J)$ is Kähler, then it can not be biholomorphically equivalent to any projective space $\mathbb{C} P(n)$.

## 8. Kählerian sectional curvature

Let $M$ be a Kähler manifold of complex dimension $n, x \in M$ and let $P$ be a plane in $T_{x} M$, that is, a real 2-dimensional subspace of $T_{x} M$. Let $X, Y$ be an orthonormal base of $P$. Define $\rho(P)$, the angle between $P$ and $J(P)$, by

$$
\cos \rho(P)=|g(X, J Y)|
$$

where $g$ is the metric on $M$. Denote by $K(P)$ the sectional curvature of $P$. Then the Kählerian sectional curvature of $P$ is denoted $K^{*}(P)$ and given by

$$
K^{*}(P)=\frac{4 K(P)}{1+3 \cos ^{2} \rho(P)}
$$

In our case to the maximal flag manifold $\mathbb{F}$, normalizing $A_{\alpha}$ and $S_{\beta}, \alpha, \beta \in \Pi$, then they are an orthonormal base for $\mathfrak{q}$. If $P=\operatorname{span}\left\{A_{\alpha}, S_{\beta}\right\} \subset \mathfrak{q}$ we have

$$
\begin{aligned}
\cos \rho(P) & =\left|\Lambda\left(S_{\alpha}, J\left(S_{\beta}\right)\right)\right|, \\
& =\left|\Lambda\left(A_{\alpha},-\varepsilon_{\beta} A_{\beta}\right)\right|, \\
& =\left|\lambda_{\alpha}\left\langle A_{\alpha}, A_{\beta}\right\rangle\right| .
\end{aligned}
$$

Thus $\cos \rho(P)$ is different from zero only when $\beta= \pm \alpha$ and in this case $\cos \rho(P)=1$, because of the normalization of the base. Thus,

$$
K^{*}(P)=K(P)=-4 \lambda_{\alpha} \alpha\left(H_{\alpha}\right)<0
$$

So if ( $\mathbb{F}, J, \Lambda$ ) is Kähler then it can not be holomorphically isometric to any projective space $\mathbb{C} P(n)$ (see [10] p. 369).

Given the results about curvatures in $\mathbb{F}$, one question appears in order to continue this work: Is it possible to characterize, with this behavior, flag manifolds in the same way that projective spaces are characterized?

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